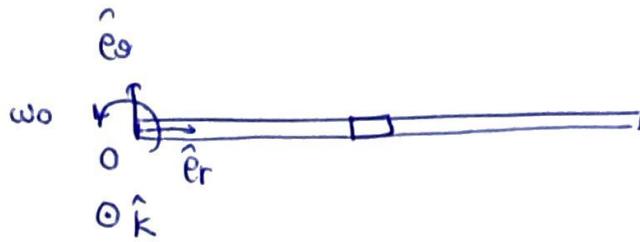


[1]



$$(a) \vec{a} = (\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta + \ddot{\theta}\hat{e}_k$$

$$r = \frac{L}{2}, \dot{r} = \ddot{r} = 0$$

$$\dot{\theta} = \omega_0, \ddot{\theta} = 0$$

$\ddot{z} = 0$ (motion in fixed horizontal plane)

$$\text{so, } \boxed{\vec{a} = -\frac{L}{2}\omega_0^2\hat{e}_r.}$$

$$(b) \begin{array}{c} \text{Free body diagram of a particle of mass } m \\ \text{Forces: Tension } \vec{T}, \text{ Weight } \vec{W}, \text{ Normal force } \vec{N} \\ \vec{F}_s \end{array} \quad \begin{aligned} \vec{W} &= -mg\hat{k} \\ \vec{N} &= N_z\hat{e}_z + N_\theta\hat{e}_\theta \\ \vec{T} &= -T\hat{e}_r \\ \vec{F}_s &= k\frac{L}{2}\hat{e}_r \end{aligned}$$

$$\vec{F} = m\vec{a}$$

$$-mg\hat{k} + N_z\hat{e}_z + N_\theta\hat{e}_\theta - T\hat{e}_r + k\frac{L}{2}\hat{e}_r = -m\frac{L}{2}\omega_0^2\hat{e}_r$$

$$\textcircled{1} \quad T = \frac{kL}{2} + \frac{mL}{2}\omega_0^2$$

$$\boxed{T = -\left(\frac{kL}{2} + \frac{mL}{2}\omega_0^2\right)\hat{e}_r}$$

$$(c) \text{ just after the spring is cut} \quad r = \frac{L}{2}$$

$$\dot{r} = 0$$

$$T = 0.$$

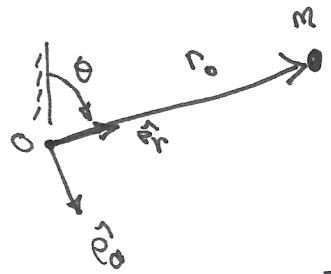
$$\textcircled{2} \quad \vec{F} = m\vec{a}$$

$$\underbrace{-mg\hat{k} + N_z\hat{e}_z + N_\theta\hat{e}_\theta + \frac{kL}{2}\hat{e}_r}_{\text{cancel}} = m[(\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta] = m\vec{a}$$

$$\textcircled{3} \quad \frac{kL}{2} = m(\ddot{r} - r\dot{\theta}^2)$$

$$\boxed{\vec{a} = \frac{kL}{2m}\hat{e}_r.}$$

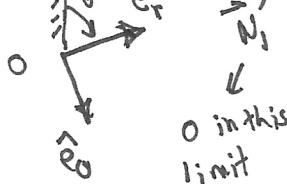
$$[2] \quad a) \quad \vec{a} = (\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_{\theta} + \ddot{z}\hat{k}$$



Here, $r = r_0 \text{ const}$ $\dot{r} = \ddot{r} = 0$
 $\dot{\theta} = \omega \text{ const}$ $\ddot{\theta} = 0$
 $z = 0 \Rightarrow \ddot{z} = 0$

so $\vec{a} = -r_0 \omega^2 \hat{e}_r$

$$b) \quad \vec{N}_2 = -N_2 \hat{e}_\theta \quad \vec{F}_f = -F_f \hat{e}_r \quad \vec{a} \text{ remains as in (a) for this limit}$$



$$\vec{W} = mg [-\cos\theta \hat{e}_r + \sin\theta \hat{e}_\theta]$$

$\vec{F} = m\vec{a}$ leads to ...

$\hat{e}_r: -F_f - mg \cos\theta = -m r_0 \omega^2$ (1)

$\hat{e}_\theta: -N_2 + mg \sin\theta = m(0)$ (2)

In this limit $F_f = \mu N_2$ from (2) $N_2 = mg \sin\theta$

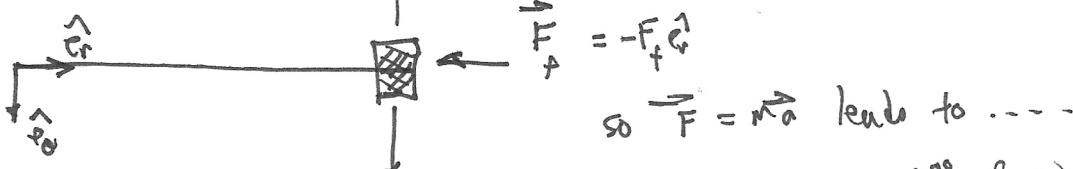
so (1) becomes $-\mu mg \sin\theta - mg \cos\theta = -m r_0 \omega^2$
 $\theta = \theta_0$

so $\omega = \sqrt{(\mu g \sin\theta_0 + g \cos\theta_0)/r_0}$

units are rad/s ✓

(c) For $r = l$, $\theta = 90^\circ \dots$ Here \dot{r}, \ddot{r} are not zero anymore ...

$$-N_2 \hat{e}_\theta = \vec{N}_2 \quad \text{so } \vec{a} = (\ddot{r} - lw^2)\hat{e}_r + 2\dot{r}w\hat{e}_\theta$$



$$\vec{F}_f = -F_f \hat{e}_r$$

so $\vec{F} = m\vec{a}$ leads to ...

$\hat{e}_r: -F_f = m(\ddot{r} - lw^2)$ (3)

$\hat{e}_\theta: -N_2 + mg = 2\dot{r}w$ (4)

However, we know $v = |\vec{v}| = \sqrt{\dot{r}^2 + l^2 w^2} = \sqrt{r^2 + l^2 w^2}$ so $\dot{r} = \sqrt{V^2 - l^2 w^2}$

we know $F_f = \mu N_2$

so (4) becomes $N_2 = mg - 2mw\sqrt{V^2 - l^2 w^2}$

and so $F_f = \mu [mg - 2mw\sqrt{V^2 - l^2 w^2}]$

so $\vec{F}_{\text{radial}} = \vec{N}_2 + \vec{F}_f = (mg - 2mw\sqrt{V^2 - l^2 w^2})(-\hat{e}_\theta - \mu \hat{e}_r)$