

MATH 121B. MIDTERM 1. 2020 SPRING

Total 50 points

- (1) Are they vector spaces? Just true or false. (5 points)
- The points in \mathbb{R}^2 satisfying $x + y = 1$.
 - The points in \mathbb{R}^3 satisfying $x + y + z = 0$.
 - The points in \mathbb{R}^3 satisfying $x^2 + y^2 + z^2 = 0$.
 - The points in \mathbb{R}^3 satisfying $xyz = 0$.
 - The set of polynomials $f(t)$ such that degree of $f(t)$ is at most 5, and satisfies $f(1) = 0$.
- (2) Let V be the vector space of smooth functions on the interval $[0, 1]$. Are the following $\phi : V \rightarrow \mathbb{R}$ linear functions on V ? Just true or false. (5 points)
- $\phi(f) = f(1/2)$, that is, ϕ sends an element $f(t) \in V$ to its value at $t = 1/2$.
 - $\phi(f) = \int_0^1 f(t) dt$
 - $\phi(f) = \int_0^1 f(t)^2 dt$
 - $\phi(f) = f'(1/3) + f''(2/3)$
 - $\phi(f) = f(1/3) \cdot f(2/3)$
- (3) Let V be a vector space of dimension 3 with basis e_1, \dots, e_3 . Let $\tilde{e}_1 = e_1, \tilde{e}_2 = e_1 + e_2, \tilde{e}_3 = e_1 + e_2 + e_3$ be a new basis of V . (10 points)
- What is the dimension of $V \otimes V$? (2 pts)
 - Write down a basis of $V \wedge V$ using e_i s. (2 pts)
 - Suppose we have vector $\mathbf{v} = 3e_2 + 5e_3$, can you express \mathbf{v} in the basis \tilde{e}_i ? (3 pts)
 - Suppose we have a tensor $T = e_2 \otimes e_3$, can you express T in the basis \tilde{e}_i ? (3 pts)
- (4) Let $V = \mathbb{R}^2$ with coordinates (x, y) and with $g = dx^2 + dy^2$. Introduce a new basis $\mathbf{e}_1 = (-1, 0)$ and $\mathbf{e}_2 = (-1, 1)$ of V . Introduce new linear coordinates (u, v) on \mathbb{R}^2 , such that $u(\mathbf{e}_1) = 1, u(\mathbf{e}_2) = 0$ and $v(\mathbf{e}_1) = 0, v(\mathbf{e}_2) = 1$. (10 points)
- Let $\mathbf{v} = (1, 1)$ (in the (x, y) coordinate system). Write \mathbf{v} as a linear combination of \mathbf{e}_1 and \mathbf{e}_2 . (5 points)
 - What is the metric tensor g (or ds^2 in Boas term), expressed using du and dv ? (5 points)
- (5) Let (u, v) be a new set of coordinates near $(0, 0)$ on \mathbb{R}^2 , which is related to the Cartesian coordinate as the following. (20 points)

$$x = u + (u^2 - v^2)/2, \quad y = v + uv$$

(where we require $u > -1/2$.)

- what is ds^2 in du, dv ? (10 points)
- Let $f = u^2 - v^2$, what is the gradient of f ? (5 points)
- Let $V = u \frac{\partial}{\partial v} - v \frac{\partial}{\partial u}$ be a vector field, (in Boas notation, $V = u\mathbf{a}_v - v\mathbf{a}_u$). What is the divergence of V ? (5)

1. SOLUTION

- (1) Are they vector spaces? Just true or false. (5 points)
- The points in \mathbb{R}^2 satisfying $x + y = 1$. False
 - The points in \mathbb{R}^3 satisfying $x + y + z = 0$. True
 - The points in \mathbb{R}^3 satisfying $x^2 + y^2 + z^2 = 0$. True or False both OK. If we had been working over \mathbb{C} , then it is False. Since we are working over \mathbb{R} , the actual solution is just the origin, hence it is a trivial linear space.
 - The points in \mathbb{R}^3 satisfying $xyz = 0$. False.
 - The set of polynomials $f(t)$ such that degree of $f(t)$ is at most 5, and satisfies $f(1) = 0$. True.
- (2) Let V be the vector space of smooth functions on the interval $[0, 1]$. Are the following $\phi : V \rightarrow \mathbb{R}$ linear functions on V ? Just true or false. (5 points)
- $\phi(f) = f(1/2)$, that is, ϕ sends an element $f(t) \in V$ to its value at $t = 1/2$. True
 - $\phi(f) = \int_0^1 f(t) dt$ True
 - $\phi(f) = \int_0^1 f(t)^2 dt$ False
 - $\phi(f) = f'(1/3) + f''(2/3)$ True
 - $\phi(f) = f(1/3) \cdot f(2/3)$ False
- (3) Let V be a vector space of dimension 3 with basis e_1, \dots, e_3 . Let $\tilde{e}_1 = e_1, \tilde{e}_2 = e_1 + e_2, \tilde{e}_3 = e_1 + e_2 + e_3$ be a new basis of V . (10 points)
- What is the dimension of $V \otimes V$? (2 pts) 9
 - Write down a basis of $V \wedge V$ using e_i s. (2 pts) $e_1 \wedge e_2, e_1 \wedge e_3, e_2 \wedge e_3$
 - Suppose we have vector $\mathbf{v} = 3e_2 + 5e_3$, can you express \mathbf{v} in the basis \tilde{e}_i ? (3 pts)
 - Suppose we have a tensor $T = e_2 \otimes e_3$, can you express T in the basis \tilde{e}_i ? (3 pts)

For the last two problem, we can plug in $e_2 = \tilde{e}_2 - \tilde{e}_1$ and $e_3 = \tilde{e}_3 - \tilde{e}_2$, to get

$$\mathbf{v} = 3(\tilde{e}_2 - \tilde{e}_1) + 5(\tilde{e}_3 - \tilde{e}_2)$$

and

$$T = e_2 \otimes e_3 = (\tilde{e}_2 - \tilde{e}_1) \otimes (\tilde{e}_3 - \tilde{e}_2).$$

Then, one may open the parenthesis and expand if one want.

- (4) Let $V = \mathbb{R}^2$ with coordinates (x, y) and with $g = dx^2 + dy^2$. Introduce a new basis $\mathbf{e}_1 = (-1, 0)$ and $\mathbf{e}_2 = (-1, 1)$ of V . Introduce new linear coordinates (u, v) on \mathbb{R}^2 , such that $u(\mathbf{e}_1) = 1, u(\mathbf{e}_2) = 0$ and $v(\mathbf{e}_1) = 0, v(\mathbf{e}_2) = 1$. (10 points)
- Let $\mathbf{v} = (1, 1)$ (in the (x, y) coordinate system). Write \mathbf{v} as a linear combination of \mathbf{e}_1 and \mathbf{e}_2 . (5 points)

$$\mathbf{v} = e_2 - 2e_1$$

- What is the metric tensor g (or ds^2 in Boas term), expressed using du and dv ? (5 points) $u_1 = u, u_2 = v$ are dual basis of $\mathbf{e}_1, \mathbf{e}_2$, hence the coefficients in front of $du_i \otimes du_j$ is $g(e_i, e_j)$, we get

$$\begin{aligned} g &= g(e_1, e_1)du \otimes du + g(e_1, e_2)du \otimes dv + g(e_2, e_1)dv \otimes du + g(e_2, e_2)dv \otimes dv \\ &= du \otimes du + du \otimes dv + dv \otimes du + 2dv \otimes dv. \end{aligned}$$

- (5) Let (u, v) be a new set of coordinates near $(0, 0)$ on \mathbb{R}^2 , which is related to the Cartesian coordinate as the following. (20 points)

$$x = u + (u^2 - v^2)/2, \quad y = v + uv$$

(where we require $u > -1/2$.)

(a) what is ds^2 in du, dv ? (10 points)

(b) Let $f = u^2 - v^2$, what is the gradient of f ? (5 points)

(c) Let $V = u \frac{\partial}{\partial v} - v \frac{\partial}{\partial u}$ be a vector field, (in Boas notation, $V = u\mathbf{a}_v - v\mathbf{a}_u$). What is the divergence of V ? (5)

We plug in $dx = (1 + u)du - vdv$ and $dy = (1 + u)dv + vdu$ into $ds^2 = dx^2 + dy^2$, we get

$$ds^2 = [(1 + u)^2 + v^2](du^2 + dv^2)$$

It is a orthogonal coordinate.

$$(2) \nabla f = g^{uu} \partial_u f \partial_u + g^{vv} \partial_v f \partial_v = \frac{2u \partial_u - 2v \partial_v}{(1+u)^2 + v^2}$$

$$(3) \nabla \cdot V = \frac{1}{\sqrt{g}} \partial_i (\sqrt{g} V^i) = \frac{1}{(1+u)^2 + v^2} (\partial_u ((-1 + u)^2 + v^2)v) + \partial_v ((1 + u)^2 + v^2)u =$$