

Physics 7A - Midterm 1 Solution
Fall 2018 (Hallatschek)
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1. (a) Horizontally, the car moves at a constant speed $v_0 \cos \theta$, while vertically it has an initial speed $v_0 \sin \theta$ and experiences a negative acceleration g . So

$$x = v_0 \cos \theta t, \quad y = v_0 \sin \theta t - \frac{1}{2} g t^2.$$

- (b) To make the car land at point $B(L, 0)$, we set $x = L$ and $y = 0$ in the two equations above, and eliminate t . It follows that $v_0 = \sqrt{gL / \sin 2\theta}$.
2. (a) There are four pieces of rope pulling up the system (man+plate), and each rope has the same tension F . So $4F - (M + m)g = (M + m)a$, which gives $a = 4F / (M + m) - g$.
- (b) If the man is lifted above the plate, only two pieces of ropes are pulling the man and the other two are pulling the plate. So we have $2F - Mg = Ma_M$ and $2F - mg = ma_m$. Therefore $a_M = 2F/M - g$ and $a_m = 2F/m - g$.
- Note that in (a) there is a normal force between m and M , while in (b) the normal force is absent. This makes the two scenarios different.

3. Let (x_M, y_M) be the position of the top corner of the wedge M , and (x_m, y_m) be the position of the block m . Since the block must move along the surface of the wedge, the displacement of m relative to M must "fit" the surface, as shown in the left figure below. Namely, the **constraint** of the motion is

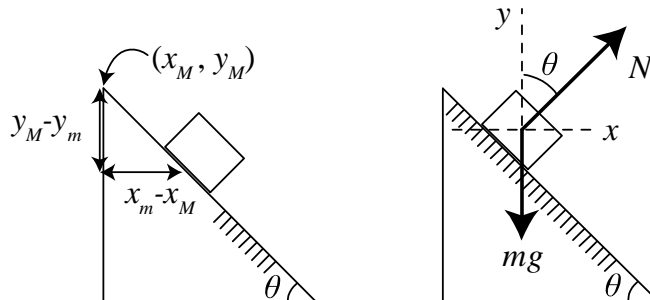
$$\tan \theta = \frac{y_M - y_m}{x_m - x_M}, \quad \text{or } y_M - y_m = (x_m - x_M) \tan \theta.$$

Differentiating the equation above with respect to time twice, and using the fact that $\ddot{x}_M = a$, $\ddot{y}_M = 0$, we get $-\ddot{y}_m = (\ddot{x}_m - a) \tan \theta$. From the free body diagram below, we also have:

$$N \sin \theta = m\ddot{x}_m, \quad \text{and } N \cos \theta - mg = m\ddot{y}_m.$$

Eliminating N from these two equations, and using $\theta = \pi/4$, we solve for \ddot{x}_m and \ddot{y}_m :

$$\ddot{x}_m = \frac{a + g}{2}, \quad \ddot{y}_m = \frac{a - g}{2}$$



4. See the free body diagram below. Since the car is climbing up a circle of radius R using the static friction force f_s , and at the same time rotating about the center with speed v , it follows that

$$\begin{aligned} N - mg \cos \theta &= \frac{mv^2}{R}, \\ mg \sin \theta &= f_s. \end{aligned}$$

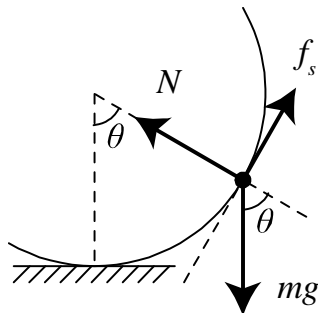
Not falling means $N \geq 0$, and not slipping implies $f_s \leq \mu_s N$. Imposing these two conditions to the two equations above, we get

$$\left\{ \begin{array}{l} \cos \theta + \frac{v^2}{gR} \geq 0 \quad (\text{not falling}), \\ \mu_s \geq \frac{\sin \theta}{\cos \theta + v^2/gR} \quad (\text{not slipping}), \end{array} \right. \quad \text{for all } \theta.$$

Since $\cos \theta$ can be as negative as -1 (when $\theta = \pi$, i.e., at the top of the circle), to ensure the first inequality to hold, we must require $v \geq \sqrt{gR}$. (To ensure the second inequality to hold, we need both $v > \sqrt{gR}$, and $\mu_s \geq 1/\sqrt{(v^2/gR)^2 - 1}$. But we don't need these results for the exam.)

- (a) From the analysis above, the car has to move at a speed $v > v_0 = \sqrt{gR}$ to not fall off from the track.
- (b) If $v < v_0 = \sqrt{gR}$, the car starts to slip when

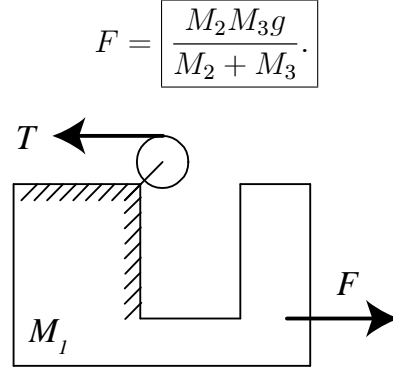
$$\mu_s = \frac{\sin \theta}{\cos \theta + v^2/gR}.$$



5. (a) The mass M_3 is pulling the rope connecting M_2 and M_3 , so both M_2 and M_3 have the same acceleration a . The equation of motion for M_2 and M_3 are $T = M_2a$ and $M_3g - T = M_3a$, respectively. Solving these two equations for a and T , we obtain

$$a = \frac{M_3g}{M_2 + M_3}, \text{ and } T = \frac{M_2M_3}{M_2 + M_3}g.$$

In the free body diagram of M_1 below, this tension T is *pushing* M_1 to the left, so the force F has to oppose it to make M_1 still:



- (b) The tension T has to balance M_3 in the vertical direction, so $T = M_3g$. But the same T also needs to pull M_2 such that M_2 has the same acceleration as the entire system, so $T = M_2a$. Hence $a = M_3g/M_2$. The force F that moves entire system $M_1 + M_2 + M_3$ with acceleration a should have magnitude

$$F = (M_1 + M_2 + M_3) \frac{M_3g}{M_2}.$$

- (c) Assume M_1 has acceleration $-a\hat{e}_x$, and M_2 has acceleration $a'\hat{e}_x$, both relative to ground. Then relative to M_1 , the mass M_2 has acceleration $(a' + a)\hat{e}_x$. Since the rope has fixed length, $a' + a$ is also the downward acceleration of M_3 . Therefore, we can write

$$\begin{aligned} T &= M_2a', \\ M_3g - T &= M_3(a' + a). \end{aligned}$$

Eliminate a' , we get $T = M_2M_3(g - a)/(M_2 + M_3)$. This tension is pushing M_1 and M_3 (via the wall next to M_3) to the left with acceleration $-a\hat{e}_x$, so

$$\frac{M_2M_3}{M_2 + M_3}(g - a) = (M_1 + M_3)a.$$

Solving this equation for a , it follows that

$$a = \frac{\mu g}{1 + \mu}, \text{ where } \mu \equiv \frac{M_2M_3}{(M_1 + M_3)(M_2 + M_3)}.$$