

Question 1. (15 points)

c

Circle the correct answers (1 point each). Mark "T" only if the statement *must* be true without further assumptions. Justification is not needed, but incorrect answers carry a 1-point penalty, so random guessing does not help. You may leave any answer blank (0 points). You will also not get a negative total score on any group of five questions.

T F If the coefficient matrix A has a pivot position in every row, then the system $Ax = b$ has a unique solution. *every column*

T F The range of the linear transformation $x \mapsto Ax$ is the column space of A . ✓

T F If the columns of an $n \times n$ matrix span \mathbf{R}^n , then they are linearly independent. *A vectors span \mathbf{R}^n are indep.*

T F For any $n \times n$ matrices A, B, C , we have $(ABC)^T = C^T B^T A^T$.

T F If a set of vectors in \mathbf{R}^n is linearly dependent, then it contains more than n vectors. *$C^T(AB)^T = C^T(B^T A^T)$* $\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$

T F If the linear system $Ax = b$ is inconsistent, then the coefficient matrix A does not have a pivot position in every column. *every row*

T F The linear system $Ax = 0$ has more than one solution whenever there are free variables.

T F If S is a linearly dependent collection of vectors, then each vector in S is a linear combination of the other vectors.

T F The nullspace of a 3×4 matrix must contain infinitely many vectors. $\begin{bmatrix} * & \cdot & \cdot & \cdot \\ * & \cdot & \cdot & \cdot \\ * & \cdot & \cdot & \cdot \end{bmatrix}$

T F If A is a 4×4 matrix and the system $Ax = e_j$ is consistent for each vector of the standard basis e_1, \dots, e_4 of \mathbf{R}^4 , then A is invertible. $\begin{bmatrix} \cdot & \cdot & \cdot & \cdot & 1 & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 1 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & 1 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & 0 & 1 \end{bmatrix}$

T F The dimensions of the row space and the column space of any $m \times n$ matrix A agree.

T F If one row in the echelon form of the augmented matrix of a system is $[0 \ 0 \ 0 \ 1 \ 0]$, then the system is inconsistent.

T F If a finite set S of vectors spans \mathbf{R}^n , then some subset of S forms a basis of \mathbf{R}^n .

T F The map $T : \mathbf{R}^2 \rightarrow \mathbf{R}^2$ which reflects points about the line $y = 1$ is linear.

T F The first row of a matrix product AB is the first row of A multiplied on the right by B .

Question 2. (12 points, 10+2)

(a) For the matrix A below, find bases of the nullspace, column space, row space and left nullspace. Make sure your method is clear.

(b) For what values of a, b does $[3, 5, a, b]$ lie in the row space? Explain.

$$A = \begin{bmatrix} 1 & 2 & 2 & 4 \\ 2 & 3 & 3 & 2 \\ 4 & 7 & 7 & 10 \end{bmatrix}$$

↑ ↑
pivot columns

a)

$$\left[\begin{array}{cccc|cccc} 1 & 2 & 2 & 4 & 1 & 0 & 0 & 0 \\ 2 & 3 & 3 & 2 & 0 & 1 & 0 & 0 \\ 4 & 7 & 7 & 10 & 0 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\substack{R_2 - 2R_1 \\ R_3 - 4R_1}} \left[\begin{array}{cccc|cccc} 1 & 2 & 2 & 4 & 1 & 0 & 0 & 0 \\ 0 & -1 & -1 & -6 & -2 & 1 & 0 & 0 \\ 0 & -1 & -1 & -6 & -4 & 0 & 1 & 0 \end{array} \right] \xrightarrow{\substack{R_3 - R_2 \\ R_1 + 2R_2 \\ R_2 \cdot (-1)}} \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & -8 & -3 & 2 & 0 & 0 \\ 0 & 1 & 1 & 6 & 2 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -2 & -1 & 1 & 0 \end{array} \right]$$

↑ ↑
pivot columns

basis of $\text{Col}(A) = \text{pivot columns of } A = \left\{ \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 7 \end{bmatrix} \right\}$

basis of $\text{Row}(A) = \text{pivot rows in } \text{rref}(A) = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ -8 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \\ 6 \end{bmatrix} \right\}$

$$3 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -8 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 1 \\ 1 \\ 6 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \\ 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \\ 5 \\ 6 \end{bmatrix} \quad \checkmark$$

basis of $\text{LNul}(A) = \text{rows corresponding to } 0 \text{ rows in } \text{rref}(A) = \left\{ \begin{bmatrix} -2 \\ -1 \\ 1 \\ 0 \end{bmatrix} \right\}$

basis of $\text{Nul}(A)$ is expressed in terms of free variables:

$$\begin{bmatrix} 1 & 0 & 0 & -8 \\ 0 & 1 & 1 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{array}{l} x_1 - 8x_4 = 0 \\ x_2 + x_3 + 6x_4 = 0 \\ x_3 = x_3 \\ x_4 = x_4 \end{array} \rightarrow \begin{array}{l} x_1 = 8x_4 \\ x_2 = -x_3 - 6x_4 \\ x_3 = x_3 \\ x_4 = x_4 \end{array} \quad \vec{x} = x_3 \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 8 \\ -6 \\ 0 \\ 1 \end{bmatrix}$$

basis of $\text{Nul}(A) = \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 8 \\ -6 \\ 0 \\ 1 \end{bmatrix} \right\}$

b) $\left[\begin{array}{ccc|c} 1 & 0 & 3 & 3 \\ 0 & 1 & 5 & 5 \\ 0 & 1 & a & a \\ -8 & 6 & b & b \end{array} \right] \xrightarrow{R_4 + 8R_1} \left[\begin{array}{ccc|c} 1 & 0 & 3 & 3 \\ 0 & 1 & 5 & 5 \\ 0 & 1 & a & a \\ 0 & 6 & b+24 & b+24 \end{array} \right] \xrightarrow{\substack{R_3 - R_2 \\ R_4 - 6R_2}} \left[\begin{array}{ccc|c} 1 & 0 & 3 & 3 \\ 0 & 1 & 5 & 5 \\ 0 & 0 & a-5 & a-5 \\ 0 & 0 & b-6 & b-6 \end{array} \right]$

to be in $\text{Row}(A)$, this must be consistent, so $a-5=0$ and $b-6=0$

$[3, 5, a, b]$ is in $\text{Row}(A)$ for: $a=5$ $b=6$

Question 3. (10 points)

A linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ sends $[1, 2]^T$ to $[1, 2, 3]^T$ and $[3, 4]^T$ to $[3, 4, 5]^T$.

(a) Find $T([5, 6]^T)$.

(b) Find a vector $\vec{v} \in \mathbb{R}^2$ with $T(\vec{v}) = [7, 8, 7]^T$, or else explain why no such vector exists.

$$\left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 2 & 4 & 0 & 1 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & -2 & -2 & 1 \end{array} \right] \xrightarrow{-\frac{1}{2}R_2} \left[\begin{array}{cc|cc} 1 & 3 & 1 & 0 \\ 0 & 1 & 1 & -\frac{1}{2} \end{array} \right] \xrightarrow{R_1 - 3R_2} \left[\begin{array}{cc|cc} 1 & 0 & -2 & \frac{3}{2} \\ 0 & 1 & 1 & -\frac{1}{2} \end{array} \right]$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} = -2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 4 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \frac{3}{2} \begin{bmatrix} 1 \\ 2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = -2 T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) + T\left(\begin{bmatrix} 3 \\ 4 \end{bmatrix}\right) = -2 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \frac{3}{2} T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) - \frac{1}{2} T\left(\begin{bmatrix} 3 \\ 4 \end{bmatrix}\right) = \frac{3}{2} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

$$[T: \mathbb{R}^2 \rightarrow \mathbb{R}^3] \rightarrow [\vec{x} \rightarrow A\vec{x}] \quad A = \begin{bmatrix} T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) & T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 2 \end{bmatrix}$$

$$a) T\left(\begin{bmatrix} 5 \\ 6 \end{bmatrix}\right) = A \cdot \begin{bmatrix} 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \\ 7 \end{bmatrix}$$

$$b) T(\vec{v}) = \begin{bmatrix} 7 \\ 8 \\ 7 \end{bmatrix}$$

$$A \cdot \vec{v} = \begin{bmatrix} 7 \\ 8 \\ 7 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 1 & 0 & 7 \\ 0 & 1 & 8 \\ -1 & 2 & 7 \end{array} \right] \xrightarrow{R_3 + R_1} \left[\begin{array}{cc|c} 1 & 0 & 7 \\ 0 & 1 & 8 \\ 0 & 2 & 14 \end{array} \right] \xrightarrow{R_3 - 2R_2} \left[\begin{array}{cc|c} 1 & 0 & 7 \\ 0 & 1 & 8 \\ 0 & 0 & -2 \end{array} \right]$$

No such vector \vec{v} exists because the system $A\vec{v} = \begin{bmatrix} 7 \\ 8 \\ 7 \end{bmatrix}$ has a row $[0 \ 0 \ | \ -2]$ which is inconsistent.

Question 4. (12 points)

Determine the inverse of the following matrix by one of two methods: either by row-reduction, or by using determinants. Check your answer.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 2 & 2 & 1 \end{bmatrix}$$

$$[A \mid I_3] \sim [I_3 \mid A^{-1}]$$

$$\begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 4 & 5 & 4 & | & 0 & 1 & 0 \\ 2 & 2 & 1 & | & 0 & 0 & 1 \end{bmatrix} \xrightarrow[\substack{R_2 - 4R_1 \\ R_3 - 2R_1}]{\substack{R_2 - 4R_1 \\ R_3 - 2R_1}} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & -3 & -8 & | & -4 & 1 & 0 \\ 0 & -2 & -5 & | & -2 & 0 & 1 \end{bmatrix} \xrightarrow[\substack{R_2 \cdot (-1) \\ R_3 \cdot (-1)}]{\substack{\text{swap } R_2 \text{ and } R_3 \\ R_2 \cdot (-1) \\ R_3 \cdot (-1)}} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 2 & 5 & | & 2 & 0 & -1 \\ 0 & 3 & 8 & | & 4 & -1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 & | & -5 & 6 & -4 \\ 0 & 2 & 0 & | & -8 & 10 & -16 \\ 0 & 0 & 1 & | & 2 & -2 & 3 \end{bmatrix} \xrightarrow[\substack{R_2 - 5R_3 \\ R_1 - 3R_3}]{\substack{R_2 - 5R_3 \\ R_1 - 3R_3}} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 2 & 5 & | & 2 & 0 & -1 \\ 0 & 0 & 1 & | & 2 & -2 & 3 \end{bmatrix} \xrightarrow[\substack{R_3 \cdot 2}]{\substack{R_3 \cdot 2}} \begin{bmatrix} 1 & 2 & 3 & | & 1 & 0 & 0 \\ 0 & 2 & 5 & | & 2 & 0 & -1 \\ 0 & 0 & \frac{1}{2} & | & 1 & -1 & \frac{3}{2} \end{bmatrix} \xrightarrow{R_3 - \frac{3}{2}R_2}$$

$$\xrightarrow[\substack{\frac{1}{2}R_2 \\ R_1 - R_2}]{\substack{\frac{1}{2}R_2 \\ R_1 - R_2}} \begin{bmatrix} 1 & 0 & 0 & | & 3 & -4 & 7 \\ 0 & 1 & 0 & | & -4 & 5 & -8 \\ 0 & 0 & 1 & | & 2 & -2 & 3 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} 3 & -4 & 7 \\ -4 & 5 & -8 \\ 2 & -2 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 4 \\ 2 & 2 & 1 \end{bmatrix} \begin{bmatrix} 3 & -4 & 7 \\ -4 & 5 & -8 \\ 2 & -2 & 3 \end{bmatrix} = \begin{bmatrix} 3-8+6 & -4+10-6 & 7-16+9 \\ 12-20+8 & -16+25-8 & 28-40+12 \\ 6-8+2 & -8+10-2 & 14-16+3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \checkmark$$