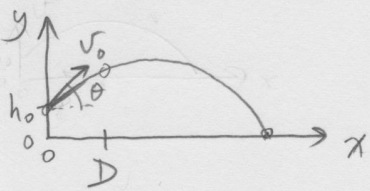


Mike Dewese 7A Midterm 1 Fall 2017

Prob. 1a) constant  $\vec{a}$ :  $a_y = g = +10 \text{ m/s}^2 = -a_y$



$$x = x_0 + v_{0x} t_n + \frac{1}{2} a_x t_n^2$$

$$D = v_0 \cos \theta t_n \Rightarrow t_n = \frac{D}{v_0 \cos \theta} \quad (1)$$

b.) const.  $\vec{a}$  projectile motion:  $|\vec{a}| = g = 10 \text{ m/s}^2$  at every point along trajectory

c.)  $v_x$  is constant.  $v_y = 0$  at highest point of trajectory  
 so  $v_{\min} = |v_x| = v_0 \cos \theta$

d.)  $y = y_0 + v_{0y} t + \frac{1}{2} a_y t^2$

$$0 = h_0 + v_0 \sin \theta t_g + \frac{1}{2} (-g) t_g^2$$

$t_g \equiv$  time to hit ground

quadratic formula:  $t_g = \frac{-v_0 \sin \theta \pm \sqrt{v_0^2 \sin^2 \theta - 4(-\frac{g}{2}) h_0}}{2(-\frac{g}{2})}$

$$t_g = \frac{v_0}{g} \sin \theta + \sqrt{\left(\frac{v_0}{g} \sin \theta\right)^2 + \frac{2h_0}{g}}$$

must be "+" since we know  $t_h > 0$

e.) find min  $v_0$  s.t.  $y(x=D) \geq h_n$ :  $\rightarrow v_0' = \min. v_0$

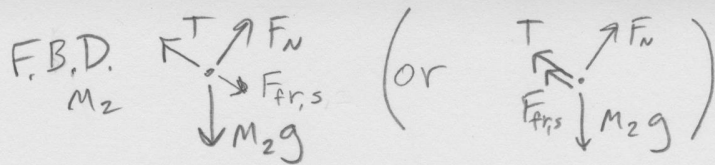
$$y_n = y_0 + v_{0y} t_n + \frac{1}{2} a_y t_n^2$$

$$(1) \Rightarrow h_n = h_0 + \frac{v_0' \sin \theta D}{v_0' \cos \theta} - \frac{1}{2} g \frac{D^2}{v_0'^2 \cos^2 \theta}$$

$$h_n - h_0 - D \tan \theta = -\frac{1}{2} g \frac{D^2}{\cos^2 \theta} \frac{1}{v_0'^2}$$

$$v_0'^2 = \frac{g D^2}{2 \cos^2 \theta D \tan \theta - (h_n - h_0)}$$

$$\text{so: } v_0 \geq \sqrt{\frac{g D^2}{2 \cos^2 \theta (D \tan \theta - (h_n - h_0))}}$$



static: NZL  $m_2$

$$x: -T + M_2 g \sin \theta + F_{fr,s} + F_{Nx} = m_2 a_x \quad (1)$$

we want the maximum  $M_1$ , so  $T$  is as big as it can be, which requires  $F_{fr,s}$  to point down the incline.

$$y: F_{fr,s,y} + F_{T,y} + F_N - m_2 g \cos \theta = m_2 a_y \quad (static)$$

$$F_N = M_2 g \cos \theta \quad (2)$$

c.) NZL:  $m_1$  z:  $T - M_1 g = m_1 a_{1z} \quad (static)$

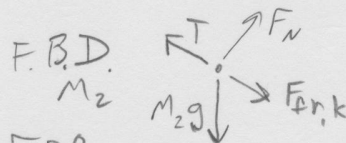
$$T = M_1 g \quad (3)$$

$$F_{fr,s} \leq \mu_s F_N \quad \text{so} \quad F_{fr,s,max} = \mu_s F_N = \mu_s M_2 g \cos \theta \quad (4)$$

$$(3) \& (4) \text{ in } (1) \Rightarrow -M_{1,max} + M_2 g \sin \theta + \mu_s M_2 g \cos \theta = 0$$

$$M_{1,max} = M_2 (\sin \theta + \mu_s \cos \theta)$$

d.) sliding up ramp:



$$NZL: M_2 \left\{ \begin{array}{l} x: -T + M_2 g \sin \theta + F_{fr,k} + F_{Nx} = m_2 a_{2x} \\ y: F_N = M_2 g \cos \theta \end{array} \right. \quad (5)$$

$$-T + M_2 g \sin \theta + \mu_k F_N = m_2 a_{2x} \quad (5)$$

$$y: F_N = M_2 g \cos \theta \quad (6)$$

$$NZL: m_1 \quad z: T - M_1 g = M_1 a_{1z} \quad (7)$$

blocks tied together with ideal rope  $\Rightarrow a_{1z} = +a_{2x} \quad (8)$

$$(6), (7), \& (8) \text{ in } (5): -M_1 a_{1z} - M_1 g + M_2 g \sin \theta + \mu_k M_2 g \cos \theta = m_2 a_{1z}$$

$$a_{1z} (m_1 + m_2) = g (-M_1 + M_2 \sin \theta + \mu_k M_2 \cos \theta)$$

$$a_{1z} = g \frac{-M_1 + M_2 \sin \theta + \mu_k M_2 \cos \theta}{M_1 + M_2} \quad (9)$$

$$e.) (9) \text{ in } (7) \Rightarrow T = M_1 \left( g + g \frac{-M_1 + M_2 \sin \theta + \mu_k M_2 \cos \theta}{M_1 + M_2} \right)$$

$$T = g M_1 M_2 \left( \frac{1 + \sin \theta + \mu_k \cos \theta}{M_1 + M_2} \right)$$

3. d.) uniform circular motion  $a_y = \frac{v^2}{R}$  (1)

NZL walter  $\uparrow$   $F_{\text{plane}} - Mg = Ma_y = -\frac{Mv^2}{R}$

$$F_{\text{plane}} = \frac{Mv^2}{R} - Mg = M\left(\frac{v^2}{R} - g\right)$$

b.)  $a = \frac{v^2}{R}$  NZL walter  $\left\{ \begin{array}{l} x: F_{p,x} = ma_x = \frac{Mv^2}{R} \quad (F_{wr,x} = 0) \\ y: F_{p,y} + F_{wr,y} - Mg = Ma_y = 0 \end{array} \right.$

so  $\vec{F}_{wr} + \vec{F}_p = \left(\frac{Mv^2}{R}, Mg\right) \Rightarrow |\vec{F}_{wr} + \vec{F}_p| = \sqrt{\frac{M^2v^4}{R^2} + M^2g^2}$   
 $= M\sqrt{\frac{v^4}{R^2} + g^2}$

c.)  $[A] = \frac{m}{s}$   $[B] = \frac{m}{s^4}$   $[C] = \frac{m}{s}$   $[D] = \frac{m}{s^2}$

d.) at highest point,  $v_h = 0$ :  $\frac{dh}{dt}\bigg|_{t'} = C - 2Dt' = 0$   $t' = \frac{C}{2D}$  (2)  $t' = \text{time to reach highest point}$

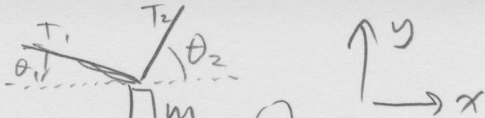
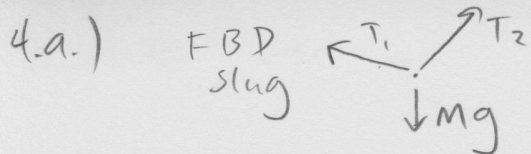
$$v(t') = A + B \frac{C^3}{8D^3}$$

e.) at highest point, horizontal component of  $\vec{a}$  points along direction of motion, so:  $a_x = \frac{dv}{dt}$

$$\frac{dv}{dt}\bigg|_{t'} = 3Bt'^2 = 3B \frac{C^2}{4D^2} = 3 \cdot 0.1 \frac{200^2}{4 \cdot 10^2} \frac{m}{s^2}$$

$$= 3 \times 10^{-1+4-2} \frac{m}{s^2}$$

$$= 30 \frac{m}{s^2}$$



NZL slug

$$x: -T_1 \cos \theta_1 + T_2 \cos \theta_2 + F_{gx} = m a_x \rightarrow 0 \text{ stationary} \quad (1)$$

$$y: T_1 \sin \theta_1 + T_2 \sin \theta_2 - mg = m a_y \rightarrow 0 \text{ stationary} \quad (2)$$

$$(1): T_2 = T_1 \frac{\cos \theta_1}{\cos \theta_2} \quad \text{in } (2) \Rightarrow T_1 \sin \theta_1 + T_1 \frac{\cos \theta_1}{\cos \theta_2} \sin \theta_2 = mg$$

$$T_1 = \frac{mg}{\sin \theta_1 + \cos \theta_1 \tan \theta_2}$$

b.)  $\theta_1 = \theta_2 = \theta$  in (1)  $\Rightarrow -T_1 \cos \theta + T_2 \cos \theta = 0$

$$T_1 = T_2 \quad (3)$$

c.) NZL slug

$$y: T_1 \sin \theta + T_2 \sin \theta - mg = m a_y = m a \leftarrow \text{upward accel.}$$

(1) still holds because  $a_x = 0 \Rightarrow (3) \Rightarrow 2T \sin \theta = mg + ma$

$$T_1 = T = \frac{m(a+g)}{2 \sin \theta}$$

d.) NZL slug

$$x: -T_1 \cos \theta + T_2 \cos \theta = m a_x = m a' \leftarrow \text{accel. to the right} \quad (4)$$

$$y: T_1 \sin \theta + T_2 \sin \theta = mg \Rightarrow T_2 = \frac{mg - T_1 \sin \theta}{\sin \theta} \quad (5)$$

$$(5) \text{ in } (4) \Rightarrow -T_1 \cos \theta + \frac{mg - T_1 \sin \theta}{\sin \theta} \cos \theta = m a'$$

$$T_1 (\cos \theta + \cos \theta) = \frac{mg \cos \theta}{\sin \theta} - m a'$$

$$T_1 = \left( \frac{mg \cos \theta}{\sin \theta} - m a' \right) \frac{1}{2 \cos \theta}$$

$$T_1 = \frac{m}{2} \left( \frac{g}{\sin \theta} - \frac{a'}{\cos \theta} \right)$$

e.) max  $a'$  occurs when  $T_1 \rightarrow 0$ , since we can't have a "-" tension. What would happen if we tried to exceed this  $a'$  value is that the slug would lift up, and not have purely horizontal acceleration.

$$T_1 = 0 \Rightarrow \frac{0}{\sin \theta} = \frac{a'_{\max}}{\cos \theta} \Rightarrow a'_{\max} = g \frac{\cos \theta}{\sin \theta}$$