

UNIVERSITY OF CALIFORNIA, BERKELEY
MECHANICAL ENGINEERING
ME 106, FLUID MECHANICS
ODK/MIDTERM 2, FALL 2015

Last name: _____
First name: _____
Student ID: _____
Discussion: _____

Notes:

- You solution procedure should be legible and complete for full credit (use scratch paper as needed).
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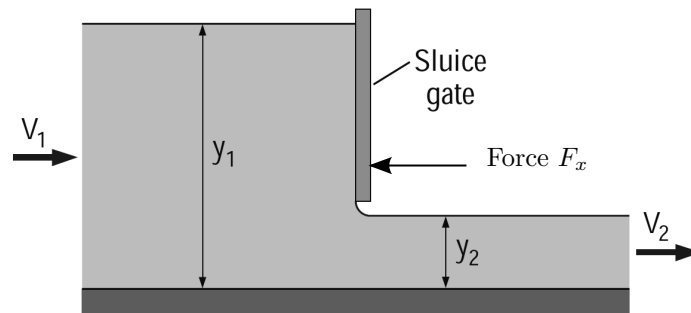
Question	Grade
1	
2	
3	
Total:	

1. Consider the unsteady, incompressible, 2D flow described by the velocity field

$$u = y^2 + t$$
$$v = x^2$$

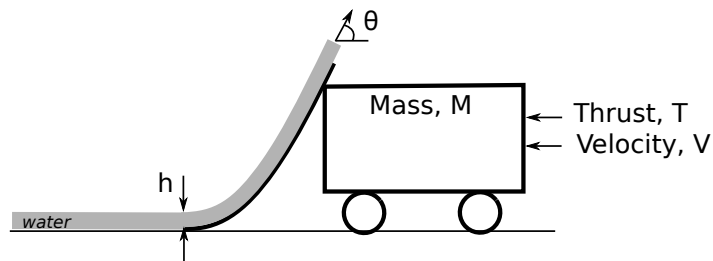
- (a) Find the equation, $x(y)$ or $y(x)$, for the streamline passing through point $(0, 0)$ at time $t = 0$.
- (b) Find the equations, $x(t)$ and $y(t)$, describing a pathline originating at point $(0, 0)$ at time $t = 0$.
- (c) Calculate the acceleration of a fluid particle at point $(0, 0)$ at time $t = 0$.

2. A sluice gate of width b into the page controls the flow of water by raising or lowering a vertical plate. The water exerts a force \mathbf{F} on the gate. Let ρ be the water density and other variables be as shown in the diagram. Disregarding the wall shear forces at the solid surfaces, and assuming steady, uniform flow:
- Solve for the horizontal component of the force, F_x , the water imposes on the gate. Express answer in terms of $(\rho, y_1, y_2, b, g$ and $V_1)$
 - Based on the expression you derived above, derive an expression for y_2 when F_x is a maximum. Assume V_1 and y_1 remain constant.



3. A vehicle of mass M scoops stationary water of density ρ with depth h and width b into the page, creating an upward jet with angle θ . Assume the incoming and outgoing stream of water on the scoop have the same area. Neglect air drag, wheel friction and gravity effects.

- (a) Determine the thrust T to maintain a constant acceleration a in terms of the variables given.
- (b) Assume that the thrust is removed ($T = 0$), hence the rocket decelerates from initial velocity V_0 at $t = 0$. Based on the expression you derived above, find the expression for the velocity $V(t)$ as a function of time (note: $a = \frac{dV}{dt}$).



Summary of Equations:

Chapter 4:

Equation for streamlines	$\frac{dy}{dx} = \frac{v}{u}$
Acceleration	$\mathbf{a} = \frac{\partial \mathbf{V}}{\partial t} + u \frac{\partial \mathbf{V}}{\partial x} + v \frac{\partial \mathbf{V}}{\partial y} + w \frac{\partial \mathbf{V}}{\partial z}$
Material derivative	$\frac{D(\cdot)}{Dt} = \frac{\partial(\cdot)}{\partial t} + (\mathbf{V} \cdot \nabla)(\cdot)$
Streamwise and normal components of acceleration	$a_s = V \frac{\partial V}{\partial s}, \quad a_n = \frac{V^2}{\mathcal{R}}$
Reynolds transport theorem (restricted form)	$\frac{DB_{\text{sys}}}{Dt} = \frac{\partial B_{\text{cv}}}{\partial t} + \rho_2 A_2 V_2 b_2 - \rho_1 A_1 V_1 b_1$
Reynolds transport theorem (general form)	$\frac{DB_{\text{sys}}}{Dt} = \frac{\partial}{\partial t} \int_{\text{cv}} \rho b \, dV + \int_{\text{cs}} \rho b \mathbf{V} \cdot \hat{\mathbf{n}} \, dA$
Relative and absolute velocities	$\mathbf{V} = \mathbf{W} + \mathbf{V}_{\text{cv}}$

Chapter 5:

Conservation of mass	$\frac{\partial}{\partial t} \int_{\text{cv}} \rho \, dV + \int_{\text{cs}} \rho \mathbf{V} \cdot \hat{\mathbf{n}} \, dA = 0$
Mass flowrate	$\dot{m} = \rho Q = \rho AV$
Average velocity	$\bar{V} = \frac{\int_A \rho \mathbf{V} \cdot \hat{\mathbf{n}} \, dA}{\rho A}$
Steady flow mass conservation	$\sum \dot{m}_{\text{out}} - \sum \dot{m}_{\text{in}} = 0$
Moving control volume mass conservation	$\frac{\partial}{\partial t} \int_{\text{cv}} \rho \, dV + \int_{\text{cs}} \rho \mathbf{W} \cdot \hat{\mathbf{n}} \, dA = 0$
Deforming control volume mass conservation	$\frac{DM_{\text{sys}}}{Dt} = \frac{\partial}{\partial t} \int_{\text{cv}} \rho \, dV + \int_{\text{cs}} \rho \mathbf{W} \cdot \hat{\mathbf{n}} \, dA = 0$
Force related to change in linear momentum	$\frac{\partial}{\partial t} \int_{\text{cv}} \mathbf{V} \rho \, dV + \int_{\text{cs}} \mathbf{V} \rho \mathbf{V} \cdot \hat{\mathbf{n}} \, dA = \sum \mathbf{F}_{\text{contents of the control volume}}$
Moving control volume force related to change in linear momentum	$\int_{\text{cs}} \mathbf{W} \rho \mathbf{W} \cdot \hat{\mathbf{n}} \, dA = \sum \mathbf{F}_{\text{contents of the control volume}}$
Vector addition of absolute and relative velocities	$\mathbf{V} = \mathbf{W} + \mathbf{U}$