

Physics #7B - Fall 2014

Dr. Winoto - Final Exam

Solution to the Exam 20141218 .

1. Helmholtz coils & anti-Helmholtz coils .

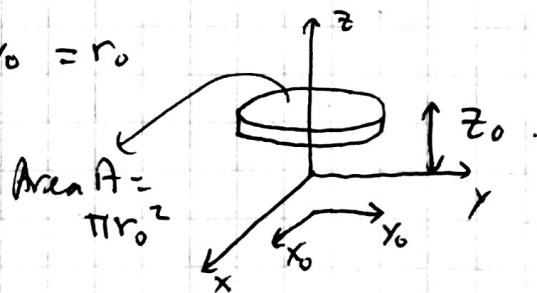
a). By symmetry (cylindrical symmetry) & Ampere's Law

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 I_{enc} , \quad B_\phi = 0 \quad \text{for both (1a) \& (1b):}$$

Helmholtz & anti-Helmholtz .

For (1a), it is enough (to get full credit) to show $B_x = B_y = 0$ on the x-y plane, but one can show this more generally in the neighborhood of the origin :

Consider a Gaussian pill box of thickness dz , centered co-axial with the z axis at a distance $z_0 \ll a$ from the origin, with radius x_0 or $y_0 = r_0$



$$\oint_S \vec{B} \cdot d\vec{a} = 0 .$$

$$\int_{\text{top}} \vec{B} \cdot d\vec{a} + \int_{\text{bottom}} \vec{B} \cdot d\vec{a}$$

$$= \int_0^{r_0} B_z(z+dz, r) 2\pi r dr - \int_0^{r_0} B_z(z, r) 2\pi r dr$$

$$= \int_0^{r_0} \frac{dB_z}{dz} (2\pi r dr) dz$$

$$= \int_0^{r_0} (4 \text{const. } z_0^3 \cdot 2\pi r dr) dz$$

$$= \text{const. } \pi r_0^2 z_0^3 dz$$

$\vec{B}_r \perp d\vec{a}$
& does not contribute
to flux .

$$B_z(z) = B_0 + \text{const. } z^4$$

$$\int_{\text{side}} \vec{B} \cdot d\vec{a} = B_r \cdot 2\pi r_0 dz$$

$$\text{Since } \oint \vec{B} \cdot d\vec{a} = 0 \Rightarrow \int_{\text{top}} + \int_{\text{bottom}} = - \int_{\text{side}}$$

$$\therefore B_r \cdot 2\pi r_0 dz = - \text{const.} \cdot \pi r_0^2 z_0^3 dz$$

$$\boxed{\begin{aligned} |B_r| &\cong \text{const.} \cdot r_0 z_0^3 \\ B_z &\cong B_0 + \text{const.} \cdot z_0^4 \end{aligned}}$$

In the limit: $\frac{r_0}{a} \ll 1$ & $\frac{z_0}{a} \ll 1$:

$$|B_r| = 0 \quad (+ \text{order } (z^4))$$

$$B_z = B_0 \quad (+ \text{order } (z^4))$$

1b). anti-Helmholtz coils:

$$B_z(z) = \alpha z \hat{z} \quad ; \quad \left. \frac{\partial B_z}{\partial z} \right|_{z=0} = \alpha$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\text{Also, just as in 1a). } B_\phi = 0 \Rightarrow \frac{\partial B_x}{\partial y} = 0 = \frac{\partial B_y}{\partial x}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0$$

$$\text{By symmetry: } \frac{\partial B_x}{\partial x} = \frac{\partial B_y}{\partial y}$$

$$\therefore 2 \frac{\partial B_x}{\partial x} = -\alpha \Rightarrow \frac{\partial B_x}{\partial x} = \frac{\partial B_y}{\partial y} = -\frac{\alpha}{2}$$

$$\Rightarrow \therefore B_x(x) = -\frac{\alpha}{2} x \hat{x} \quad ; \quad B_y(y) = -\frac{\alpha}{2} y \hat{y}$$

2. London eq. & diamagnetism in superconductivity (40 pts):

$$\vec{J} = -\frac{ne^2}{mc} \vec{A}$$

Taking the curl of the Ampere's law and substituting the London equation, we have:

$$\Rightarrow \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) = \vec{\nabla} \times (\mu_0 \vec{J})$$

Since we have a steady-state time-independent case

we can set the displacement current $j_d = \epsilon_0 \frac{\partial E}{\partial t} = 0$.

$$\Rightarrow \vec{\nabla}(\vec{\nabla} \cdot \vec{B}) - \vec{\nabla}^2 \vec{B} = \vec{\nabla} \times \mu_0 \vec{J} = \vec{\nabla} \times \left(-\frac{\mu_0 ne^2}{mc} \vec{A}\right)$$

Since $\vec{\nabla} \cdot \vec{B} = 0$ and $\vec{B} = \vec{\nabla} \times \vec{A}$:

$$\Rightarrow -\vec{\nabla}^2 \vec{B} = -\frac{\mu_0 ne^2}{mc} \vec{B}$$

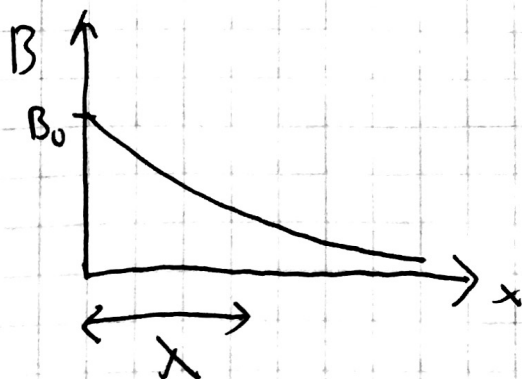
a). $\Rightarrow \nabla^2 \vec{B} = \frac{1}{\lambda^2} \vec{B}$ where $\lambda = \left(\frac{mc}{\mu_0 ne^2}\right)^{1/2}$.

b).

$$\vec{B}(x=0) = B_0 \hat{z}, \quad \vec{B}(x \rightarrow \infty) = 0$$

$$\vec{\nabla}^2 \vec{B} = \frac{\partial^2 \vec{B}}{\partial x^2} = \frac{1}{\lambda^2} \vec{B} \quad \leftarrow$$

$$\boxed{\vec{B}(x) = B_0 e^{-x/\lambda} \hat{z}}$$



(the other solution $e^{+x/\lambda}$ does not satisfy the boundary condition at $x \rightarrow \infty$)

3. \vec{E} & \vec{B} of a moving electric dipole:

$$v_x = \frac{4}{5}c \quad \gamma = \frac{1}{\sqrt{1-v^2/c^2}} = \frac{1}{\sqrt{1-16/25}} = \frac{5}{3}$$

$$t' = t = 0$$

a/. $x' = d$

$$x = \gamma(x' + vt') = \gamma x' = \gamma d$$

$$\begin{aligned} \vec{E}(r=x, \theta=90^\circ) &= \frac{P}{4\pi\epsilon_0} \frac{1}{x^3} (-\hat{z}) \\ &= \frac{-P}{4\pi\epsilon_0} \frac{1}{\gamma^3 d^3} \hat{z} \end{aligned}$$

$$\vec{E}'_z = \gamma E_z$$

$$\vec{E}'(x', 0, 0) = -\frac{1}{\gamma^2} \frac{P}{4\pi\epsilon_0} \frac{1}{d^3} \hat{z} = -\frac{9}{25} \frac{P}{4\pi\epsilon_0} \frac{1}{d^3} \hat{z}$$

$$\vec{B}'(x', 0, 0) = +\frac{\vec{v}}{c^2} \times \vec{E}' = \frac{36}{125} \frac{P}{4\pi\epsilon_0 c} \frac{1}{d^3} \hat{y}$$

b/. $z' = d$

$$z = z' = d$$

$$\begin{aligned} \vec{E}(r=z, \theta=0) &= \frac{P}{4\pi\epsilon_0} \frac{z}{z^3} \hat{z} \\ &= \frac{P}{4\pi\epsilon_0} \frac{z}{d^3} \hat{z} \end{aligned}$$

$$\vec{E}'(0, 0, z'=d) = \gamma \frac{P}{4\pi\epsilon_0} \frac{z}{d^3} \hat{z} = \frac{10}{3} \frac{P}{4\pi\epsilon_0} \frac{1}{d^3} \hat{z}$$

$$\vec{B}'(0, 0, z'=d) = +\frac{\vec{v}}{c^2} \times \vec{E}' = -\frac{8}{3} \frac{P}{4\pi\epsilon_0 c} \frac{1}{d^3} \hat{y}$$

4. Diamagnetism in a classical H :

a). $F_{\text{centrifugal}} = F_c$
 $\frac{m v_0^2}{a_0} = \frac{1}{4\pi\epsilon_0} \frac{e^2}{a_0^2}$

$$v_0^2 = \frac{1}{m} \frac{1}{4\pi\epsilon_0} \frac{e^2}{a_0}$$

$$v_0 = \sqrt{\frac{1}{m} \frac{1}{4\pi\epsilon_0} \frac{e^2}{a_0}} \approx \frac{1}{137} c$$

b). Period = $\frac{2\pi a_0}{v_0} = 1.5 \times 10^{-16}$ sec.

c). $B_{\text{solenoid}} = \vec{B} = \mu_0 n I \hat{z}$

$$\vec{B}(t) = \mu_0 n I(t) \hat{z} \quad n = 5 \times 10^4 / \text{m}$$

~~Amperian~~ loop of radius $r = a_0$

$$\oint \vec{E} \cdot d\vec{l} = - \frac{d\Phi}{dt} \quad ; \quad \vec{E} = E_\phi \text{ by symmetry}$$

$$E_\phi \cdot 2\pi r = - \pi r^2 \cdot \dot{B}(t) \quad (r = a_0)$$

$$E = E_\phi = \frac{1}{2} r \dot{B}(t) \quad \text{clockwise (looking from top)}$$

Force on electron : $F_e = -eE$

$$= \frac{1}{2} e r \dot{B} \quad \text{counterclockwise}$$

$$\dot{B} = \mu_0 n \dot{I}$$

$$\dot{B} = \mu_0 n \frac{I_0}{T}$$

d). Acceleration:

$$a_\phi = \frac{F_e}{m} = \frac{\frac{1}{2} e r \dot{B}}{m} = \frac{e r \dot{B}}{2m}$$

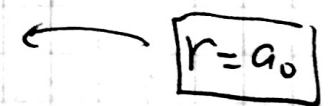
Tangential velocity:

$$\int dv = \int a_\phi dt$$

$$v(t) - v_0 = a_\phi t$$

$$\Rightarrow v(t) = v_0 + \frac{e r \dot{B}}{2m} t$$

$$= v_0 + \frac{e r B(t)}{2m}$$



4e).

$$\Delta V = v(T) - v_0$$

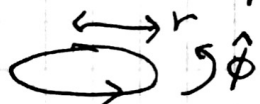
$$= \frac{e a_0 B(T)}{2m} = \frac{e a_0 B(T)}{2m}$$

$$= \frac{e a_0 \mu_0 n I_0}{2m}$$

$$\boxed{\Delta V = 5.8 \text{ m/sec}}$$

5). Displacement current & Induced B-field :

a). Consider an Amperian loop of radius r deep inside the solenoid :



$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi}{dt} \quad \vec{E} = E_\phi \hat{\phi} \text{ by symmetry}$$

$$E_\phi \cdot 2\pi r = -\pi r^2 \frac{dB}{dt} \quad ; \quad \frac{dB}{dt} = \mu_0 n \omega I_0 \cos \omega t$$

$$E_\phi = -\frac{1}{2} r \frac{dB}{dt} \hat{\phi}$$

$$\Rightarrow \boxed{E_\phi(r) = -\frac{1}{2} \mu_0 n \omega r I_0 \cos \omega t}$$

b). $\vec{j}_d = \epsilon_0 \frac{\partial \vec{E}}{\partial t} = +\frac{1}{2} \epsilon_0 \mu_0 n \omega^2 r I_0 \sin \omega t \hat{\phi}$

$$= \frac{1}{2} \frac{\omega^2}{c^2} r n I_0 \sin \omega t \quad \text{since } c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

5c).

Induced B-field :

The modified Ampere's Law :

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 \int_S (\vec{j} + \vec{j}_d) \cdot d\vec{a} .$$

Let's consider the contribution from \vec{j}_d only :

$$\oint_C \vec{B}_{ind} \cdot d\vec{l} = \mu_0 \int_S \vec{j}_d \cdot d\vec{a} .$$

\vec{j}_d is cylindrical current / circularly symmetric and linearly proportional to $|\vec{r}|$. We can calculate the B-field

\vec{B}_{ind} due to \vec{j}_d by calculating the B-field due to solenoid

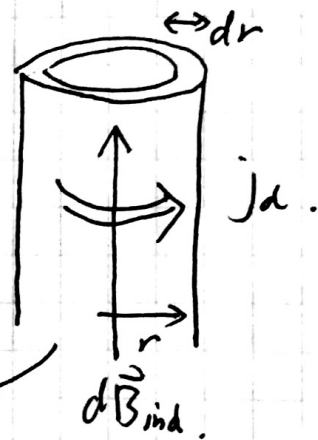
of \vec{j}_d : radius r and thickness dr , and integrating

over dr :

$$\text{surface current: } \vec{j}_d(r) = \vec{j}_d(r) \cdot dr$$

$$d\vec{B}_{ind} = \mu_0 \vec{j}_d(r) \hat{z}$$

$$= \mu_0 j_d(r) dr \hat{z}$$



$$\text{at } r=0 \leftarrow \vec{B}_{ind} = \int_0^a d\vec{B}_{ind} = \frac{1}{2} \mu_0 n I_0 \frac{\omega^2}{c^2} \sin \omega t \int_0^a r dr .$$

$$\vec{B}_{ind}(0) = \frac{1}{4} \left(\frac{\omega^2}{c^2} a^2 \right) \mu_0 n I_0 \sin \omega t .$$

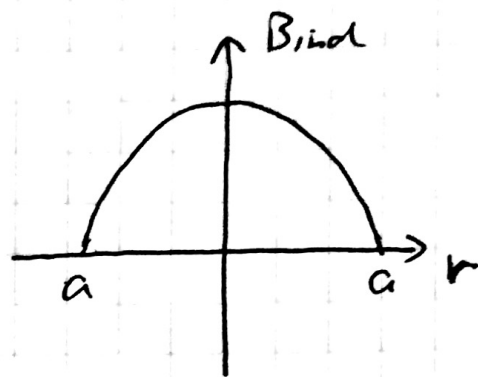
Since $d\vec{B}$ inside solenoid = $\mu_0 \vec{j}$

= 0 outside of solenoid.

$$\text{then: } \vec{B}_{ind}(r) = \int_r^a d\vec{B}_{ind} = \frac{1}{2} \mu_0 n I_0 \frac{\omega^2}{c^2} \sin \omega t \int_r^a r dr .$$

c) unit:

$$B_{ind}(r) = \frac{1}{4} \frac{\omega^2}{c^2} (a^2 - r^2) \mu_0 n I_0 \sin \omega t$$



$$B_{tot} = B_{solenoid} + B_{ind}(r)$$

$$B_{tot}(r) = \mu_0 n I_0 \sin \omega t \left[1 + \frac{1}{4} \frac{\omega^2}{c^2} (a^2 - r^2) \right]$$

d) Extra credit:

Vector potential:

$$\oint \vec{A} \cdot d\vec{l} = \int \vec{B} \cdot d\vec{a}$$

$$A_\phi \cdot 2\pi r = \underbrace{\int_{S(r)} \vec{B} \cdot d\vec{a}}_{\Phi(r)} \quad \text{for choice of gauge } \vec{\nabla} \cdot \vec{A} = 0.$$

$$\begin{aligned} \Phi(r) &= \int_0^r B_{tot}(r) \cdot 2\pi r \, dr \\ &= 2\pi \mu_0 n I \sin \omega t \int_0^r \left[1 + \frac{1}{4} \frac{\omega^2}{c^2} (a^2 - r^2) \right] r \, dr \\ &= 2\pi \mu_0 n I \sin \omega t \left[\frac{1}{2} \left(1 + \frac{1}{4} \frac{\omega^2}{c^2} a^2 \right) r^2 - \frac{1}{16} \frac{\omega^2}{c^2} r^4 \right]. \end{aligned}$$

$$A_\phi(r) = \mu_0 n I \sin \omega t \left[\frac{1}{2} \left(1 + \frac{1}{4} \frac{\omega^2}{c^2} a^2 \right) r - \frac{1}{16} \frac{\omega^2}{c^2} r^3 \right]$$