

Problem 1. (33 points total)

(a) (28 points)  $v_T = \frac{60}{3.6} = 16.67 \text{ m/s}$  (14 points for relative velocity)

$v_C = \frac{80}{3.6} = 22.22 \text{ m/s}$

Attach a translating  $xy$ -frame to the car  $C$  with the  $x$ -axis along the normal direction of the truck  $T$ . The same unit vectors  $\mathbf{i}, \mathbf{j}$  can be used in both the translating and fixed frames. Thus

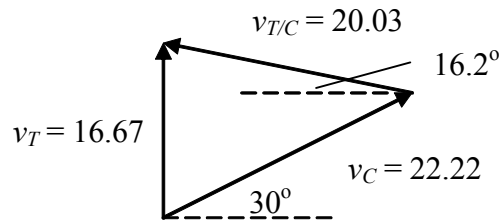
$$\mathbf{v}_T = \mathbf{v}_C + \mathbf{v}_{T/C}$$

$$\Rightarrow 16.67\mathbf{j} = 22.22 \cos 30^\circ \mathbf{i} + 22.22 \sin 30^\circ \mathbf{j} + \mathbf{v}_{T/C}$$

$$\Rightarrow \mathbf{v}_{T/C} = -19.24\mathbf{i} + 5.56\mathbf{j} \text{ m/s} \quad (3 \text{ points for answer})$$

The solution may also be obtained graphically from the vector diagram of velocities. In comparison, the absolute velocity of truck  $T$  is

$$\mathbf{v}_T = 16.67\mathbf{j}$$



Similarly, (14 points for relative acceleration)

$$a_T = \frac{v_T^2}{\rho} = \frac{16.67^2}{110} = 2.53 \text{ m/s}^2$$

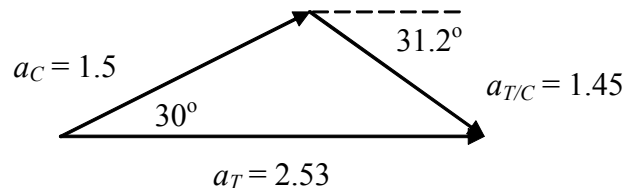
$$a_C = 1.5 \text{ m/s}^2$$

The acceleration of  $T$  relative to  $C$  is given by

$$\mathbf{a}_T = \mathbf{a}_C + \mathbf{a}_{T/C}$$

$$\Rightarrow 2.53\mathbf{i} = 1.5 \cos 30^\circ \mathbf{i} + 1.5 \sin 30^\circ \mathbf{j} + \mathbf{a}_{T/C}$$

$$\Rightarrow \mathbf{a}_{T/C} = 1.23\mathbf{i} - 0.75\mathbf{j} \text{ m/s}^2 \quad (3 \text{ points for answer})$$



(b) (5 points) A coordinate system attached to the truck  $T$  (with the  $y$ -axis in the direction of the velocity of  $T$  for example) is a rotating system. If  $\mathbf{v}_{\text{rel}}$  is the velocity of car  $C$  as observed from truck  $T$ , then  $\mathbf{v}_{\text{rel}}$  depends on the rotation of coordinate system attached to the truck. It can be shown from rigid-body kinematics that

$$\mathbf{v}_{\text{rel}} = \mathbf{v}_C - \mathbf{v}_T - \boldsymbol{\omega} \times \mathbf{r}_{C/T} \quad (\text{this is not expected})$$

$$\Rightarrow \mathbf{v}_{\text{rel}} \neq \mathbf{v}_C - \mathbf{v}_T = -\mathbf{v}_{T/C} \quad (3 \text{ points for answer})$$

Problem 2. (33 points total)

Attach  $xy$ -frame to the center of the upper pulley. Locate  $A, B$  by coordinates  $x_A$  and  $y_B$ . Since  $x_A \leq 0$ ,

$$-x_A + 2y_B = L \quad \Rightarrow \quad v_A = 2v_B \quad (7 \text{ points for constraint})$$

$$\Rightarrow \quad v_A(0) = 2v_B(0) = 6 \text{ ft/sec}$$

For block  $A$ , (10 points for block  $A$ )

$$\int \sum F_x dt = \Delta G_x \quad \Rightarrow \quad \int_0^1 (T - \mu_k N) dt = m_A v_A(1) - m_A v_A(0) \quad \longrightarrow$$

$$\Rightarrow \quad T - 0.1(10) = \frac{10}{32.2} [v_A(1) - 6] \quad (1)$$

For block  $B$ , (10 points for block  $B$ )

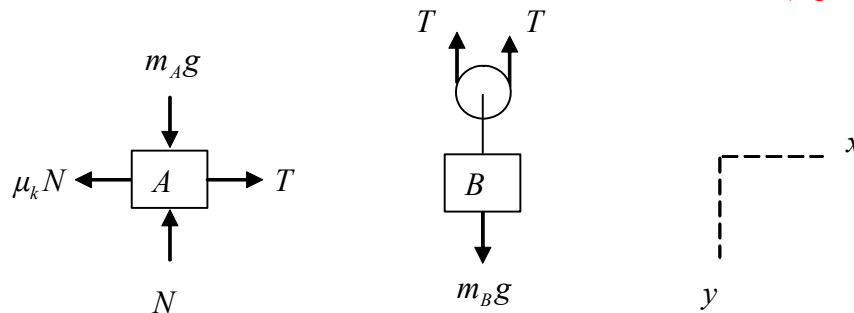
$$\int \sum F_y dt = \Delta G_y \quad \Rightarrow \quad \int_0^1 (-2T + m_B g) dt = m_B v_B(1) - m_B v_B(0) \quad \downarrow$$

$$\Rightarrow \quad -2T + 3 = \frac{3}{32.2} \left[ \frac{v_A(1)}{2} - 3 \right] \quad (2)$$

There are 2 unknowns  $v_A(1), T$  in 2 equations. Simultaneous solution gives

$$v_A(1) = 7.50 \text{ ft/sec} \quad \longrightarrow \quad (3 \text{ points for answer})$$

$$T = 1.47 \text{ lb} \quad (3 \text{ points for answer})$$



### Problem 3. (34 points total)

The solution is divided into three parts so that the impact between  $A$  and  $B$  can be treated separately.

Part 1. (10 points) Let  $v_A$  be the velocity with which the block  $A$  hits the pan  $B$ .

$$\Delta T + \Delta V_g = 0 \Rightarrow \quad m_A g h = \frac{1}{2} m_A v_A^2$$

$$\Rightarrow \quad v_A = 6.26 \text{ m/s} \quad \downarrow$$

Part 2. (10 points) Let  $v$  be the common velocity of the block  $A$  and pan  $B$  after the plastic impact. Then

$$\Delta G = 0 \quad \Rightarrow \quad m_A v_A + m_B v_B = (m_A + m_B) v$$

$$\Rightarrow \quad 30(6.26) = (30 + 10) v$$

$$\Rightarrow \quad v = 4.70 \text{ m/s} \quad \downarrow$$

Part 3. (14 points) Let  $\delta$  be the maximum deflection of the pan measured from its initial level of static equilibrium. The initial compression of the spring is

$$e = m_B g / k = 4.91 \times 10^{-3} \text{ m}$$

For the system consisting of  $A$  and  $B$ ,

$$U_{1-2} = \Delta T = -T_1$$

$$\Rightarrow (m_A + m_B)g\delta - \int_e^{e+\delta} kx dx = -\frac{1}{2}(m_A + m_B)v^2$$

$$\Rightarrow 40(9.81)\delta - 10000[(e + \delta)^2 - e^2] + 20v^2 = 0$$

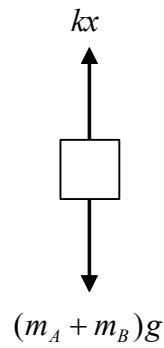
$$\Rightarrow 10000\delta^2 - 294.2\delta - 441.8 = 0$$

$$\Rightarrow \delta = 0.225 \text{ or } -0.196$$

Take the positive root to write

$$\delta = 225 \text{ mm}$$

(5 points for answer)



Position 1: at reference level

Position 2:  $\delta$  below reference