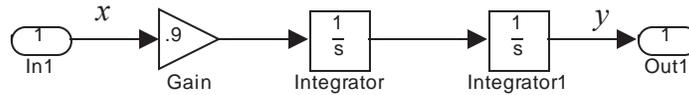


**EECS 20. Midterm No. 2 Solutions**  
**November 8, 2002.**

1. **40 points (10 points each part).** Consider the Simulink diagram shown below:



This shows an LTI system with one input and one output, both of which are continuous-time signals. The input and output are indicated by the rounded boxes, and are labeled  $x$  and  $y$ . The gain is 0.9, and the integrators both have initial condition equal to 0.

- (a) Write a differential equation (with no integrals, just derivatives) that relates the input  $x$  and the output  $y$ .

**Answer:**

$$\forall t \in \mathcal{Reals}_+, \quad 0.9x(t) = \ddot{y}(t).$$

- (b) Give the  $[A, b, c, d]$  representation of this system.

**Solution:** Let the state be the outputs of the two integrators, as follows:

$$\forall t \in \mathcal{Reals}_+, \quad z(t) = \begin{bmatrix} y(t) \\ \dot{y}(t) \end{bmatrix}$$

Hence,

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 0.9 \end{bmatrix} \quad c^T = [1 \ 0] \quad d = 0.$$

- (c) Find the frequency response  $H: \mathcal{Reals} \rightarrow \mathcal{Reals}$  of this system.

**Solution:** Let the input be  $x(t) = e^{i\omega t}$ , in which case the output must be  $H(\omega)e^{i\omega t}$ . Substituting these into the differential equation from part (a), we get

$$0.9e^{i\omega t} = H(\omega)(-\omega^2 e^{i\omega t}),$$

which we can solve for  $H(\omega)$  to get

$$H(\omega) = -0.9/\omega^2.$$

- (d) Find the output of the system if the input  $x$  is given by

$$\forall t \in \mathcal{Reals}, \quad x(t) = \cos(2t).$$

**Solution:** Write this input as

$$\forall t \in \mathcal{Reals}, \quad x(t) = 0.5(e^{i2t} + e^{-i2t}),$$

which using linearity implies that the output must be

$$\forall t \in \mathcal{Reals}, \quad y(t) = 0.5(H(2)e^{i2t} + H(-2)e^{-i2t}) = 0.5((0.9/4)e^{i2t} + (0.9/4)e^{-i2t}) = 0.2 \cos(2t).$$

2. **30 points (5 points each part).** Consider continuous-time systems with input  $x: \text{Reals} \rightarrow \text{Reals}$  and output  $y: \text{Reals} \rightarrow \text{Reals}$ . Each of the following defines such a system. For each, indicate whether it is linear (L), time-invariant (TI), both (LTI), or neither (N). Note that no partial credit will be given for these questions.

- (a)  $\forall t \in \text{Reals}, \dot{y}(t) = x(t) + 0.9y(t)$  **Answer:** LTI
- (b)  $\forall t \in \text{Reals}, y(t) = \cos(2\pi t)x(t)$  **Answer:** L
- (c)  $\forall t \in \text{Reals}, y(t) = x(t - 1)$  **Answer:** LTI
- (d)  $\forall t \in \text{Reals}, y(t) = x(t) + 0.1(x(t))^2$  **Answer:** TI
- (e)  $\forall t \in \text{Reals}, y(t) = x(t) + 0.1(x(t - 1))^2$  **Answer:** TI
- (f)  $\forall t \in \text{Reals}, y(t) = 0$  **Answer:** LTI

3. **40 points (10 points each part).** Consider a discrete-time signal  $x: \text{Integers} \rightarrow \text{Reals}$  defined by

$$\forall n \in \text{Integers}, \quad x(n) = 1 - \cos(3\pi n/4).$$

Assume this signal is sampled at 8,000 samples/second.

- (a) Give the frequency of the cosine term in Hz (cycles/second).  
**Solution:** The frequency is  $3\pi/4$  radians/sample. Divide by  $2\pi$  radians/cycle and multiply by 8000 samples/second to get 3000 Hz.
- (b) Give period of  $x$ .  
**Solution:** The period is the smallest positive integer  $p$  such that  $3\pi p/4$  is a multiple of  $2\pi$ . Thus,  $p = 8$ .
- (c) Give the fundamental frequency (in any units, but be sure to give the units).  
**Solution:**  $\omega_0 = 2\pi/p = \pi/4$  radians/sample. Alternatives:  $1/8$  cycles/sample, or  $8000/8$  cycles/second = 1000 cycles/second.
- (d) Give the coefficients  $A_0, A_1, A_2, \dots, A_K$  and  $\phi_1, \phi_2, \dots, \phi_K$  of the Fourier series expansion for  $x$ ,

$$x(n) = A_0 + \sum_{k=1}^K A_k \cos(k\omega_0 n + \phi_k)$$

where

$$K = \begin{cases} (p-1)/2 & \text{if } p \text{ is odd} \\ p/2 & \text{if } p \text{ is even} \end{cases}$$

**Solution:**  $A_0 = 1, A_1 = 0, A_2 = 0, A_3 = 1, A_4 = 0$ , and  $\phi_1 = 0, \phi_2 = 0, \phi_3 = \pi, \phi_4 = 0$ , although the phases corresponding to zero amplitude can be anything. The  $\phi_3 = \pi$  accounts for the minus sign in the definition of  $x$ .