

## Statics (E36)

## Final Examination

**Problem 1.** (20 points)

Draw the shear and moment diagrams for the beams shown in Figure 1 :

(A)  $w_0 = 10\text{N/m}$ ,  $a = 1.0\text{m}$ :

(a1) Find the reactions, (a2) Find the expressions for  $V(x)$  and Draw the shear diagram, and (a3) Find the expressions for  $M(x)$  and Draw the moment diagram ;

(B)  $M = 10\text{ N-m}$  and  $L = 5\text{m}$ .

(b1) Find the reactions, (b2) Find the expressions for  $V(x)$  and Draw the shear diagram, and (b3) Find the expressions for  $M(x)$  and Draw the moment diagram .

Hints:

$$\frac{dV}{dx} = -w(x), \text{ and } \frac{dM}{dx} = V(x) .$$

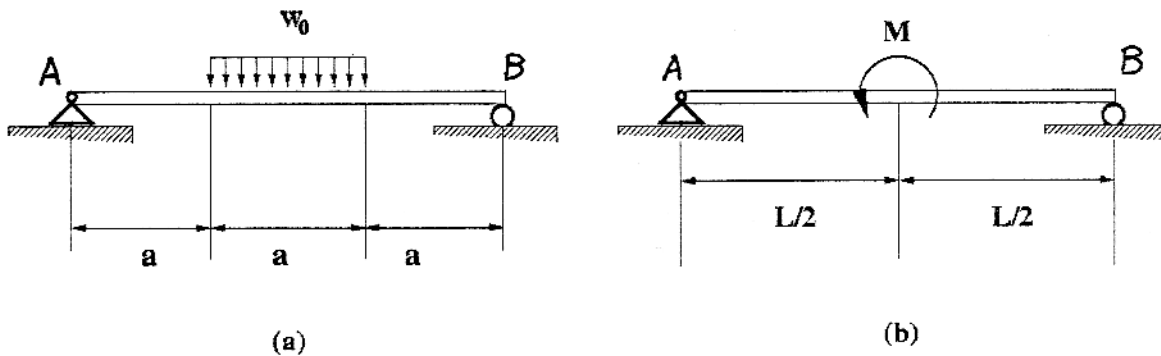


Figure 1: A simply supported beam with different load conditions

**Problem 2.** (15 points)

(1) Find the centroid of the cross-section shown in Figure 2 and set up the centroidal axes.

$$\bar{y} = \frac{\sum_i \bar{y}_i A_i}{\sum A_i}$$

(2) Find  $I_x$  with respect to the global centroidal axes.

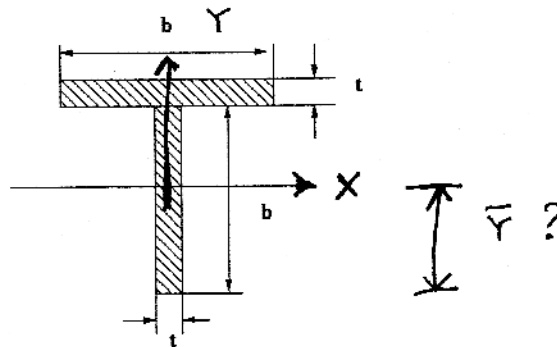


Figure 2: The cross section of a T-beam

Hints:

$$I_x = \int_A y^2 dA, \quad I_y = \int_A x^2 dA \quad (1)$$

$$I_x = (I_x)_c + d^2 A, \quad \leftarrow \text{Parallel Axis Theorem} \quad (2)$$

$$I_{\text{rectangular}} = \frac{bh^3}{12} \quad \leftarrow \text{(The genetic formula for local centroidal axis)} \quad (3)$$

**Problem 3** (15 points)

A 2.4-m-long boom is held by a ball-and-socket joint at C and by two cables AD and BE. An external load  $\mathbf{W} = -880\mathbf{j}$  is acting at point A. Determine the tension in each cable and the reaction at the point C.

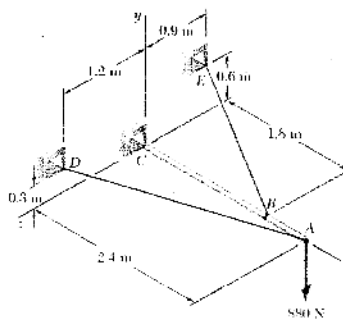


Fig. P4.116

Figure 3: A three-dimensional structure

- Draw free-body diagram for bar AC;
- Write down the vector expressions for  $\mathbf{r}_A$ ,  $\mathbf{r}_B$ ,  $\mathbf{r}_{AD} = \mathbf{r}_D - \mathbf{r}_A$ , and  $\mathbf{r}_{BE} = \mathbf{r}_E - \mathbf{r}_B$ ;
- Find the forces in the vector form,  $\mathbf{W}$ ,  $\mathbf{T}_{AD}$ , and  $\mathbf{T}_{BE}$ ;

(d) Write the vector form moment equilibrium equation,

$$\sum \mathbf{M}_C = \sum_i \mathbf{r}_{ic} \times \mathbf{F}_i = 0$$

and find  $T_{AD}$  and  $T_{BE}$ ;

(f) Write the vector form force equilibrium equation

$$\sum_i \mathbf{F}_i = 0$$

and find  $C_x$ ,  $C_y$ , and  $C_z$

Hint:

$$\mathbf{r} \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix}$$

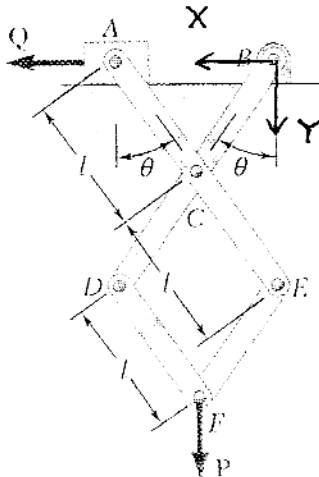


Fig. P10.50 and P10.51

**Problem 4. (20 points)**

Denoting by  $\mu_s$  the coefficient of static friction between the block attached to rod ACE and the horizontal surface, derive expressions in terms of  $P$ ,  $\mu_s$ , and  $\theta$  for the largest and smallest magnitudes of the force  $Q$  for which equilibrium is maintained.

- Draw the free-body diagram for the whole system;
- Find the ground support force  $A_y$  and the friction force acting on block A;
- Find  $x_A$ ,  $y_F$  and the virtual displacements  $\delta x_A$  and  $\delta y_F$ ;
- Write down  $\delta U$  and let  $\delta U = 0$  to find  $Q_{max}$  and  $Q_{min}$ ;

Figure 4: Friction and Virtual Work Method

**Problem 5. (15 points)**

A floor truss is loaded as shown. Determine the forces in members FI, HI, and HJ.

- Find the reactions at the point A and the point K;
- Use method of section making a cut, draw the free-body diagram of the remaining sub-structure, and then solve for internal forces  $F_{FI}$ ,  $F_{HI}$ , and  $F_{HJ}$ .

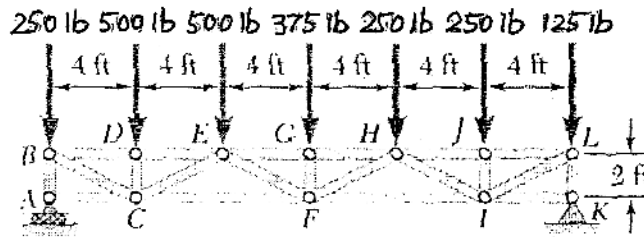
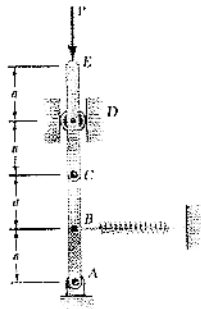
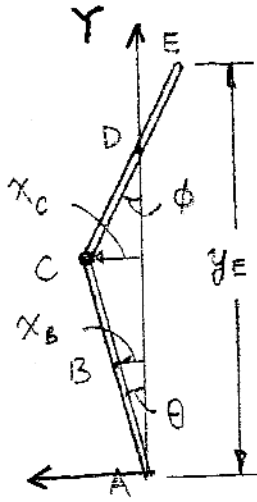


Figure 5: A Truss System with External Loads.



**SOLUTION**



**Problem 6. (15 points)**

Bar AC is attached to a hinge at A and to a spring at the point B. The spring constant is  $k$ , and it is undeformed when the bar is vertical. Find the range of values of  $P$  for which the equilibrium of the system is stable at shown the position  $\theta = 0$ .

- (a) Find  $x_c$  in terms of  $\theta$  and  $\phi$  and find the relationship between  $\theta$  and  $\phi$  when  $\theta, \phi \ll 1$ ;
- (b) Find  $x_B$  and  $y_E$  and write down the potential function for the system in terms of  $\theta, P, k$  and  $a$ ;
- (2) Show that  $\theta = 0$  is an equilibrium position by using the equilibrium condition

$$\frac{dV}{d\theta} = 0;$$

- (3) Find the range of values of  $P$  such that the equilibrium at  $\theta = 0$  is stable  $\frac{d^2V}{d\theta^2} > 0$ .

Figure 6: Equilibrium of a two-bar system.