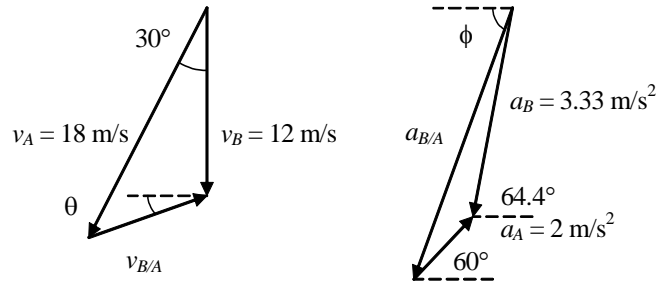


Problem 1.



(a) Since the direction of car A is constant, a coordinate system attached to A will only be translating. In the vector equation

$$\mathbf{v}_B = \mathbf{v}_A + \mathbf{v}_{B/A}$$

only the vector $\mathbf{v}_{A/B}$ is not known. Either from a graphical solution or trigonometry,

$$v_{B/A}^2 = v_B^2 + v_A^2 - 2v_B v_A \cos 30^\circ = 324 + 144 - 2(18)(12) \cos 30^\circ$$

$$\Rightarrow v_{B/A} = 9.69 \text{ m/s}$$

With an additional application of the law of cosines,

$$\theta = 21.74^\circ$$

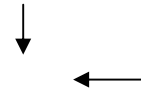
In a similar fashion,

$$\mathbf{a}_B = \mathbf{a}_A + \mathbf{a}_{B/A}$$

Observe that

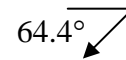
$$(a_B)_t = 3 \text{ m/s}^2$$

$$(a_B)_n = \frac{v_B^2}{\rho} = \frac{144}{100} = 1.44 \text{ m/s}^2$$



Thus

$$a_B = 3.33 \text{ m/s}^2$$



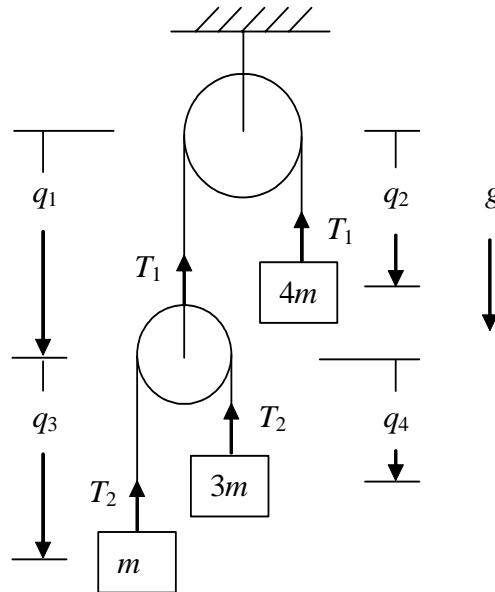
Either from a graphical solution or trigonometry,

$$a_{B/A} = 5.32 \text{ m/s}^2$$

$$\phi = 62.72^\circ$$

(b) A coordinate system attached to B is a rotating system. For example, a set of rectangular coordinates attached to B with the y-axis aligned with the velocity of B is continuously changing its direction. Thus the acceleration of car A as observed from car B is not equal to $-\mathbf{a}_{B/A}$.

Problem 2.



(a) Let T_1 be the tension in the upper string and T_2 tension in the lower string. It is obvious that $T_1 = 2T_2$. A force balance on each mass gives

$$4mg - T_1 = 4m\ddot{q}_2 \quad (1)$$

$$mg - T_2 = m(\ddot{q}_1 + \ddot{q}_3) \quad (2)$$

$$3mg - T_2 = 3m(\ddot{q}_1 + \ddot{q}_4) \quad (3)$$

Observe that $\ddot{q}_1 = -\ddot{q}_2$ and $\ddot{q}_3 = -\ddot{q}_4$. It follows that the above three equations involve only three unknowns \ddot{q}_2 , \ddot{q}_3 and T_2 . Solution yields

$$\ddot{q}_2 = \frac{1}{7}g = 1.40 \text{ m/s}^2 \quad \downarrow$$

(b) Since the masses m and $3m$ connected to the lower pulley are in motion, forces in the system are not in equilibrium. The tension in the upper string is

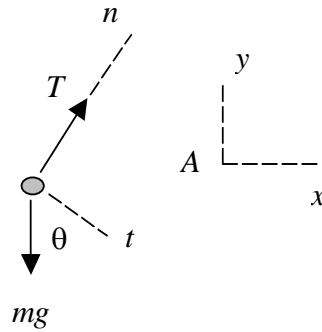
$$T_1 = 4mg - 4m\ddot{q}_2 = \frac{24}{7}mg < 4mg$$

Thus the mass $4m$ has a downward acceleration even when the total mass on each side of the upper pulley is the same.

(c) Velocity of mass $4m$ after 2 s is directed downward and is equal to

$$v = v_0 + at = \frac{2}{7}g = 2.80 \text{ m/s} \quad \downarrow$$

Problem 3.



(a) Let the rope break in position $\theta = \alpha$. Before the rope breaks, the bag travels in a circle of radius l . In any position $\theta \leq \alpha$,

$$\sum F_t = ma_t \Rightarrow mg \cos \theta = ma_t \Rightarrow \dot{v} = g \cos \theta \quad (1)$$

$$\sum F_n = ma_n \Rightarrow T - mg \sin \theta = m \frac{v^2}{l} \quad (2)$$

From kinematics and equation (1),

$$\begin{aligned} \dot{v} = \frac{dv}{d\theta} \dot{\theta} = \frac{dv}{d\theta} \frac{l\dot{\theta}}{l} = \frac{v dv}{l d\theta} = g \cos \theta &\Rightarrow \int_0^v v dv = \int_0^\theta g \cos \theta l d\theta \\ &\Rightarrow v^2 = 2gl \sin \theta \quad (3) \end{aligned}$$

When $\theta = \alpha$, $T = 2mg$. It follows from equation (2) that

$$2mg - mg \sin \alpha = m \frac{2gl \sin \alpha}{l} \Rightarrow \alpha = \sin^{-1} \frac{2}{3} = 41.81^\circ$$

(b) Set up a rectangular system with origin at A. When the rope breaks, the position of the bag is $(x_0, y_0) = (l - l \cos \alpha, -l \sin \alpha) = (2.546, -6.667)$

In that position, $v = \sqrt{2gl \sin \alpha} = 11.431$ and the distance to fall before reaching the level C is $h - |y_0| = h - 6.667 = 23.333$. Along the y-direction,

$$\begin{aligned} y = v_y t - \frac{1}{2} g t^2 &\Rightarrow -23.333 = (-11.431 \cos \alpha) t - \frac{1}{2} g t^2 \\ &\Rightarrow t = 1.479 \end{aligned}$$

Along the x-direction,

$$x = v_x t = 11.431 \sin \alpha (1.479) = 11.271$$

Thus the horizontal distance of C from A is $11.27 + x_0 = 11.27 + 2.55 = 13.82$ m